

Using Linux in Embedded Systems Where and When does it apply?

21-Apr-2006

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What is an "Embedded System"

- A combination of computer hardware and software, perhaps with additional mechanical or other components, designed to perform a dedicated function
 - Unlike a general-purpose PC, embedded systems typically have specific requirements and perform pre-defined tasks
 - The hardware and software typically is part of some larger system and expected to function without human intervention
 - Embedded systems often need to respond to events in real time
- Embedded systems can range in size from a single processing board to systems with full operating systems
 - Typical embedded system is a single-board microcomputer with software in ROM, which starts running a dedicated application as soon as power is turned on & stops only when power is turned off
- Using Linux as the operating system for embedded systems has captured the imagination of device designers

Constraints in Embedded System

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Design
Embedded systems are designed to do a given task at a low cost

- Most have specific real-time system constraints that must be met
- They may need to be very fast for some functions, but not others
- Often some parts of an embedded system need low performance compared to the primary mission of the system
- Real-time constraints can be met with a combination of dedicated hardware and software tailored to the system requirements.
- Embedded systems are typically expected to run continuously for years without maintenance
 - More careful attention is paid during software development and test than is done for desktop PC applications
 - Embedded systems avoid mechanical or moving parts as much as possible because these are unreliable
 - Human intervention may be impossible so a system must be able to restart itself even if catastrophic data corruption occurs

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Evolution in the Embedded World

- In the past, "embedded" referred to relatively small systems with few characteristics of a "computer"
 - Mostly hardware product with tiny amounts of memory and small but very efficient programs
 - May not need to communicate with other programmed devices
 - If there was an OS at all, it was lean and not very feature-rich
- Embedded projects today are more sophisticated, both in terms of features and underlying hardware
 - Most embedded systems require some type of connectivity, such as Ethernet or USB
 - Cheaper / faster processors & memory are available
 - Trying to write everything from scratch is not feasible so software reuse is more necessary than ever
 - Many of these components now exist in the public domain and in the open source community

Cost Considerations

- For high volume systems, cost usually dominates the system design
 - Use a CPU that is "good enough" for these secondary functions
 - Intentionally simplify system to keep costs as low as possible
 - Each component (including software) is selected and targeted to minimize system cost
- For low-volume systems, personal computers can often be used
 - A design choice might still be to limit the programs installed or replace the operating system with a real-time operating system
 - Special purpose hardware that is a requirement in a high volume system may be replaced by one or more high performance CPUs
- Some embedded systems may require both high performance CPUs, special hardware, and large memories to accomplish a required task.



Popular RTOS choices

- For embedded systems that use an operating system, we have more choices available today than ever before
 - There are more than we can list here, but to name a few:
 - Embedded Linux
 - VxWorks
 - QNX
 - Windows CE
 - Windows NT Embedded
 - LynxOS
 - NetBSD / OpenBSD
 - Palm OS
 - DOS
 - Inferno
 - eCos
- About 20% of embedded systems use Linux today & growing

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Why Embedded Linux?

- Linux first attracts designers because it is free to download, it comes with the source, and is compatible with a wide range of processors
- A Linux operating system gives immediate access to many useful features that would be difficult to provide with a lower order OS
 - by choosing the right packages, it is possible to easily add such features as TCP/IP, SNMP, TFTP, HTTP, VoIP and others
 - there is a rich set of drivers and other features which add to the value package



Embedded Linux Advantages

- Choosing embedded Linux brings several advantages compared to other embedded operating systems:
 - Open source kernel provides mature well tested code base with a reputation for reliability
 - A modular architecture makes it possible to customize system to meet application requirements
 - No up-front purchase costs
 - No run-time royalty costs
 - A standard programming interface
 - Inexpensive development seats or zero cost development tools
 - A worldwide support community
 - Reasonably small footprint
 - Windows CE takes 21MB compared to 2MB for Embedded Linux



Embedded Linux Disadvantages

- Embedded Linux has a few disadvantages compared to other embedded operating system choices:
 - Has to be customized / optimized for specific application to obtain minimum footprint and maximum benefit
 - Designers must have certain knowledge or skills not widely available
 - Open source
 - No common platform to rally around which distribution to choose?
 - Concerns about general-public-license contamination
 - Not generally a hard real-time solution

Memory Requirements

- A Linux kernel, combined with a few other free software utilities, can fit into the limited hardware space available in an embedded device
 - Linux micro-kernel requires only about 100 K on a Pentium CPU, including virtual memory and all core operating system functions
 - Add in the networking stack and basic utilities, a complete Linux system could still fit in 500 K of memory
- Total memory required is dictated by the applications selected for the given application, such as a Web server or SNMP agent
 - An embedded Linux system should be customized to user needs to minimize space requirements
 - A fully featured Linux kernel requires about 1 MB of memory
 - Typical installation of embedded Linux takes less than 2 MB

Linux is not a Real Time OS

- Before 2.6, the standard Linux application was not suitable for hard real-time systems for several basic architectural reasons
 - the basic Linux scheduler uses a fairness algorithm to guarantee even the lowest priority process some CPU time, even though a higher priority process may be waiting
 - when a process calls a kernel service, such as the scheduler or a device driver, this call disables interrupts and makes it impossible to pre-empt Linux until the service completes execution
 - Linux also relies on page swapping to move user code into and out of virtual memory, making timing unpredictable
- Standard Linux could still be used in embedded systems design, but just not if if the application has real-time response constraints
 - Something needed to be done ...

Adapting Linux for Real Time

- To use the 2.4 kernel in real time applications, the Linux community used patches and workarounds to deliver deterministic performance
 - One approach was to add pre-emption points within the kernel to reduce process latency but still protect critical code sections
 - A modified scheduler also ensures that the processor executes the highest priority tasks
 - Another approach was to add a small real-time kernel to handle the high-priority tasks while Linux runs as the lowest priority to schedule the remaining non-real-time tasks
 - RTAI (Real Time Application Interface) and RTLinux are two opensource projects based on this dual-kernel approach
- These patches are imperfect, but they offer a drastic improvement over the standard 2.4 Linux kernel
 - Main drawback is that they are nonstandard and require unique support and reimplementation for each kernel update

Creating Competitive Advantage www.businessaccelerators.ca Linux as a Real Time OS

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- Many real-time concepts applied to the 2.4 kernel are a permanent part of Linux in 2.6 and are standard build options
 - Numerous pre-emption points allowing the scheduler to suspend an active task and initiate a higher priority process were added
 - The kernel can be built without a page-swapping virtual-memory system that wreaks havoc on process timing
 - The process-scheduler algorithm has been re-written to speed task switching in multitasking applications
 - Improvements were made to the Linux Posix (Portable Operating System Interface for Unix) implementation
- 2.6 has updates to benefit embedded, desktop, and server systems
 - uClinux was incorporated into the kernel, allowing it to run on low cost micro-controllers without memory management
 - Yields a smaller footprint build for applications with no user interface



2.4 Kernel vs 2.6 Kernel

- So with all of that, why not move to 2.6 kernel for embedded?
- The 2.6 kernel has the following disadvantages:
 - Slower to build: takes 30 40% longer to compile than 2.4
 - Slower to boot: takes 5-15% longer to boot to multi-user mode
 - Slower to run: context switches up to 96% slower, file system latencies up to 76% slower, local communication latencies up to 80% slower, local communication bandwidth less than 50% in some cases
 - Bigger FLASH memory footprint: the compressed kernel image is 30-40% bigger
 - Bigger RAM memory footprint: the kernel needs 30-40% more RAM
- For our current embedded developments we have chosen to remain with the patched 2.4 kernel rather than move to 2.6
 - Future projects might require 2.6 for other reasons (ex. IPv6)



When to choose Linux?

- Embedded developers need to ask what they want from an OS
 - First consider does this application even need an OS?
 - Do you just need a round robin processing loop?
 - What processing hardware will be used?
 - Will it be a larger device with networking etc?
 - Do you need threading?
 - Do you need device drivers for chip peripherals?
- Linux is best suited to embedded applications that require access to higher order features (network features, SNMP, web server, etc)
 - Systems with multiple processes & interprocess communication or networking
 - Systems with mixture of real-time and non real-time requirements
- With modifications to the kernel Linux can be used for hard-real time systems



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The Licence Issue

- Discussion of Linux is incomplete without considering licence issues
- Legal ambiguity surrounding the GPL potentially impedes choice of Linux for some embedded developments
- Embedded system design is especially susceptible to GPL concerns
- The GPL as clarified by Linus Torvalds. The Linux kernel is licensed under the GPL, but with this clarification:
 - "This copyright does *not* cover user programs that use kernel services by normal system calls -- this is merely considered normal use of the kernel, and does *not* fall under the heading of 'derived work.'"
- This statement clarifies that user-space programs are not considered to be derived from Linux
 - It is also interpreted as allowing proprietary kernel modules



Practical Example

- We have built an embedded telecoms system with Ethernet, TFTP download, SNMP management interfaces and 3 layers of processor hierarchy
 - Based on a standard 2.4.24 kernel with RTAI patches added
 - Process switching measured at 15 microsecond (100 worst case) on Freescale MPC852 processor
- With static libraries, the load size still less than 4 MB as follows:
 - Kernel 0.5 MB
 - Selected GCC libraries ~1 MB
 - SNMPD 1.2 MB
 - TRAPD 1 MB



- Embedded Linux development is evolving rapidly
 - A designer has the option to choose from a variety of options for everything from the bootloader and distribution to the filesystem and GUI
 - Given this remarkable freedom of choice and a very active Linux community, embedded development on Linux has reached new levels of acceptance and usage
 - Many new handheld and embedded devices are being delivered as open boxes
- Hopefully this introductory overview of the embedded Linux space has whet your appetite and answered some of your questions
 - To aid you further in your projects, The Business Accelerators are able to help with more in-depth information on embedded Linux or help with your design efforts

